

Quantum mechanics, tensor networks and machine learning

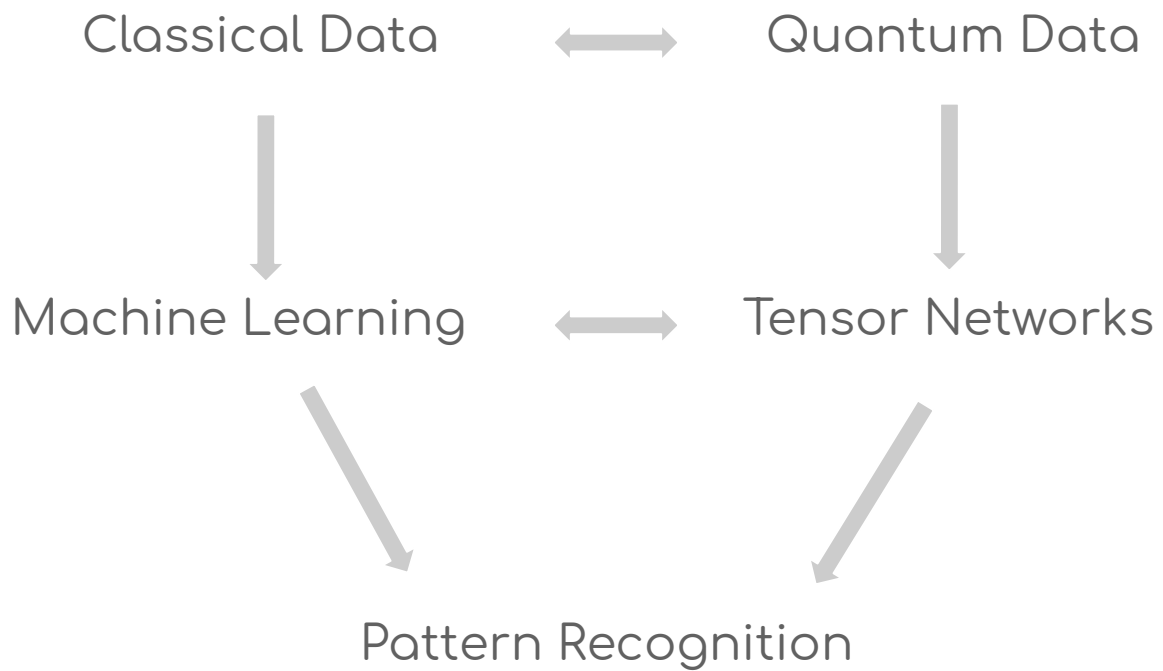
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Moritz August
- Free University Berlin:
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motivations

- Quantum mechanics and machine learning are intrinsically probabilistic theories
- Neural networks and tensor networks are two extremely successful paradigms in their respective fields
- Can we connect their mathematical formulation?
- Can we improve one by using the other?



content of the talk

1. quantum mechanics and linear algebra
 - a. wavefunctions are vectors
 - b. observables are matrices
2. linear algebra and tensor networks
 - a. Tensor networks as an efficient tool for certain problems in linear algebra
3. tensor networks and machine learning
 - a. tensor networks for probabilistic modeling
 - b. Examples for supervised and unsupervised learning

quantum mechanics

wavefunctions are vectors

↓ ↑ ↓ ↓ ↑ ↑ ↓ ↓
0 1 0 0 1 1 0 0

Notation: $0 \rightarrow (1, 0) = |0\rangle$
 $1 \rightarrow (0, 1) = |1\rangle$

$$0100 \rightarrow (1, 0) \otimes (0, 1) \otimes (1, 0) \otimes (1, 0) = |0100\rangle$$

A generic vector in this Hilbert space can be expressed as:

$$|v\rangle = \vec{v} = \sum_{\{x\}} \omega_x |x\rangle \quad \text{with} \quad \sum_{\{x\}} |\omega_x|^2 = 1$$

observables are matrices

$$|v\rangle = \vec{v} = \sum_{\{x\}} \omega_x |x\rangle$$

$$\mathcal{O}\vec{v} = \vec{u}$$

two examples

$$\left\{ \begin{array}{l} \text{energy} \\ \text{magnetization} \end{array} \right. \quad \begin{array}{l} E = \frac{\vec{v}^T H \vec{v}}{\vec{v}^T \vec{v}} \\ M = \frac{\vec{v}^T Z \vec{v}}{\vec{v}^T \vec{v}} \end{array}$$

Dynamical behavior: Schrödinger equation

$$i\hbar \frac{d\vec{v}(t)}{dt} = H\vec{v}(t) \rightarrow \vec{v}(t) = e^{-iHt/\hbar} \vec{v}(0)$$

tensor networks and linear algebra

matrix product representations

$$|v\rangle = \vec{v} = \sum_{\{x\}} \omega_x |x\rangle$$

$x : (x_1, x_2, \dots, x_n)$
 $x_i \in (0, 1)$

$$|MPS\rangle = \sum_{\{x\}} A_1^{x_1} A_2^{x_2} A_3^{x_3} \dots A_N^{x_N} |x_1 x_2 \dots x_N\rangle$$

in physics, if

- physical degrees of freedom are arranged on a line: one dimension.
- the vector fulfills an area law

then

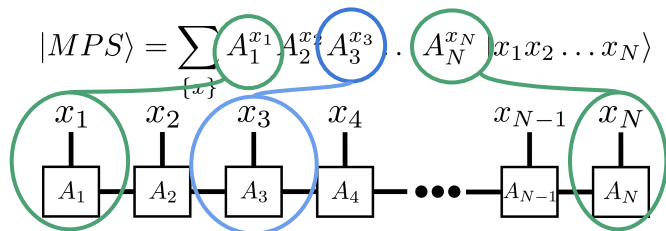
matrix product states are a faithful representation

$$x : (x_1, x_2, \dots, x_n)$$

$$x_i \in (0, 1)$$

graphical notation

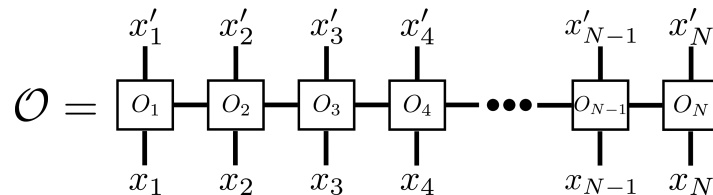
for vectors



Rank 2 tensors
at the edges

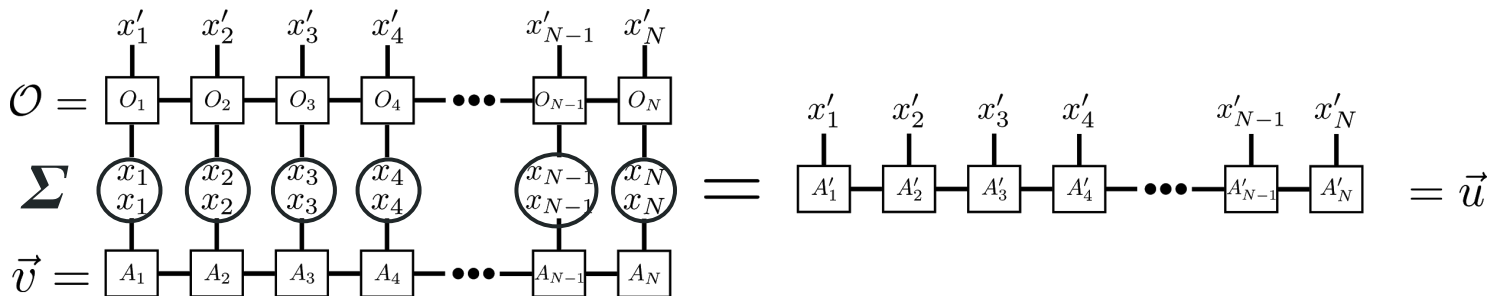
Rank 3 tensors
in the bulk

for matrices



Efficient matrix-vector multiplication

$$\mathcal{O} \vec{v} = \vec{u}$$



tensor networks and machine learning

$$|v\rangle = \vec{v} = \sum_{\{x\}} \omega_x |x\rangle$$

Matrix Product States (MPS):

$$|MPS\rangle = \sum_{\{x\}} A_1^{x_1} A_2^{x_2} A_3^{x_3} \dots A_N^{x_N} |x_1 x_2 \dots x_N\rangle$$

String Bond States (SBS):

$$|SBS\rangle = \sum_{\{x\}} \prod_j A_{1,j}^{x_1} A_{2,j}^{x_2} A_{3,j}^{x_3} \dots A_{N,j}^{x_N} |x_1 x_2 \dots x_N\rangle$$

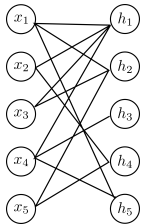
Boltzmann Machines (BM):

$$|BM\rangle = \sum_{\{x_1 x_2 \dots x_N\}} \sum_{\{h\}} \exp[\tilde{H}(\mathbf{x}, \mathbf{h})] |x_1 x_2 \dots x_N\rangle$$

Restricted Boltzmann Machines (RBM):

$$|RBM\rangle = \sum_{\{x_1 x_2 \dots x_N\}} \prod_j \cosh\left(\sum_i W_{ij} x_i\right) |x_1 x_2 \dots x_N\rangle$$

$$\tilde{H} = \sum_{ij} W_{ij} x_i h_j$$



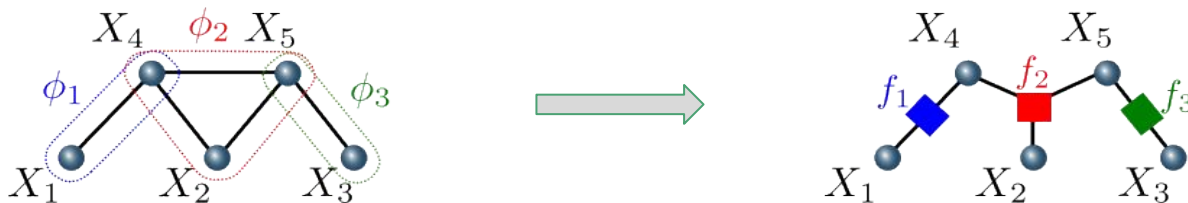
Restricted Boltzmann Machines are a subclass of string bond states

$$|RBM\rangle \rightarrow |SBS\rangle$$

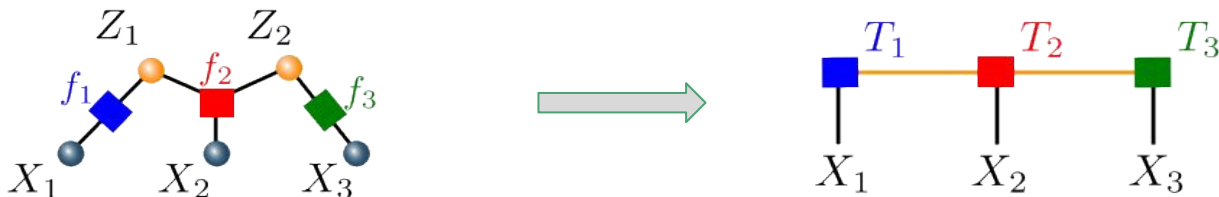
Relationship with graphical models

Graphical models are classical probabilistic models where one assumes a certain factorization of the probability density function

Without hidden units: $P(X_1, X_2, X_3, X_4, X_5) = \phi_1(X_1, X_4)\phi_2(X_4, X_2, X_5)\phi_3(X_5, X_3)$



With hidden units: $P(X_1, X_2, X_3) = \sum_{Z_1, Z_2} f_1(X_1, Z_1)f_2(X_2, Z_1, Z_2)f_3(X_3, Z_2)$

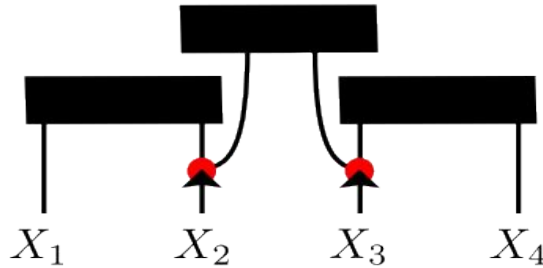
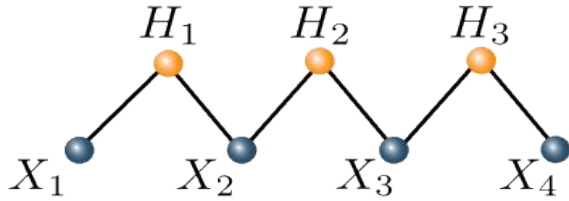


Locality of the RBM

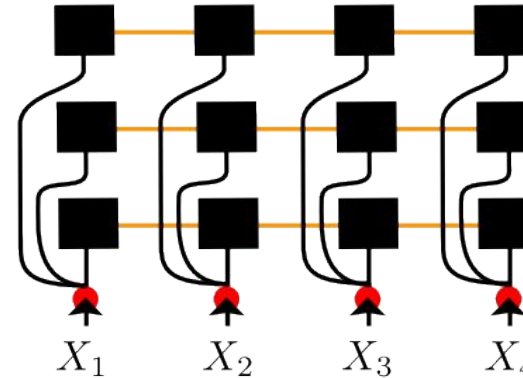
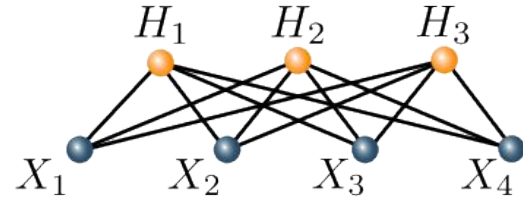
$$|RBM\rangle = \sum_{\{x_1 x_2 \dots x_N\}} \prod_j \cosh \left(\sum_i W_{ij} x_i \right) |x_1 x_2 \dots x_N\rangle$$

$$\tilde{H} = \sum_{ij} W_{ij} x_i h_j$$

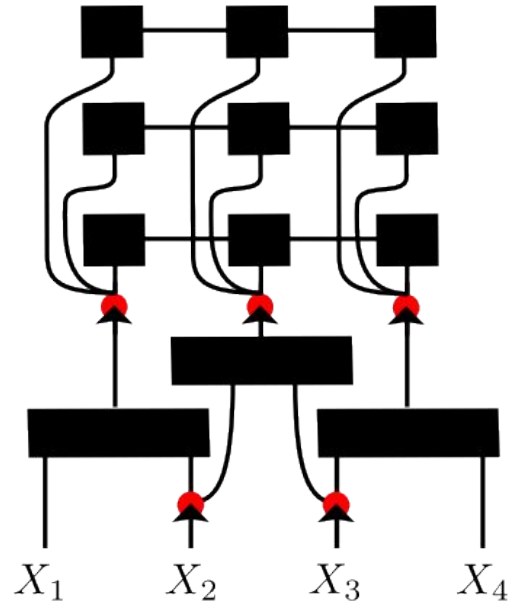
local connections



with local connections



Combining different models



classification

Image Classification

Goal: Given a dataset of images and corresponding labels, we want to predict the label of a new image

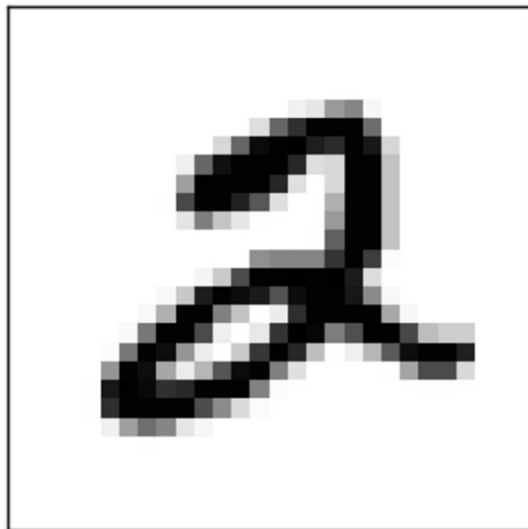


Image Classification

Goal: Given a dataset of images and corresponding labels, we want to predict the label of a new image

Choose a "model": $p(x, y) = \text{SBS}(x, y)$

Define a cost function: $-\sum_i \log(p(y_{x_i} | x_i))$

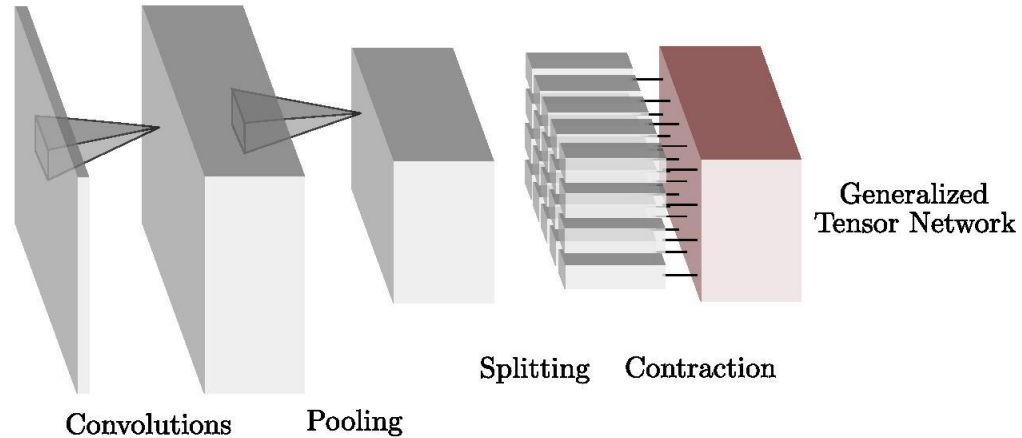


FashionMNIST

SVM	84.1%
Multilayer Perceptron	87.7%
<u>SBS</u>	89.0%
AlexNet	89.9%
<u>1-layer CNN+SBS</u>	92.3%
GoogLeNet	93.7%

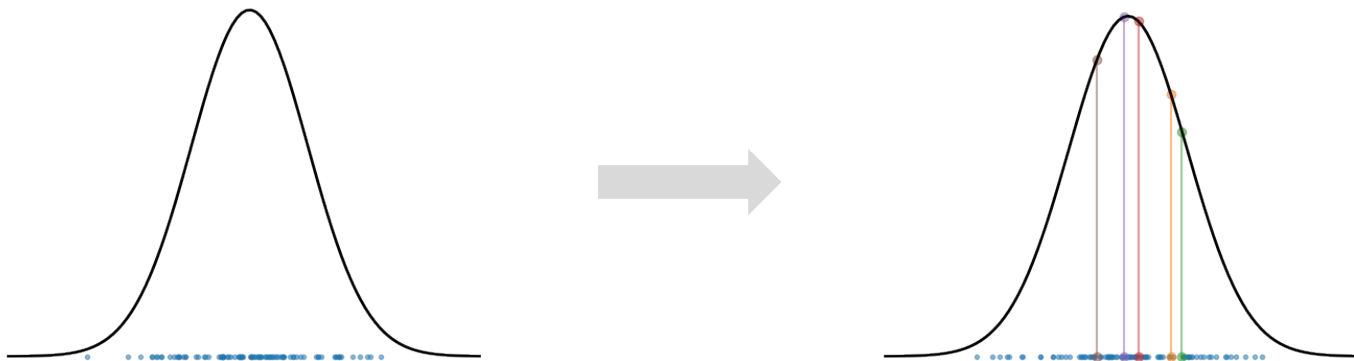


Architecture



maximum likelihood estimations

Maximum likelihood



Learn from a database:

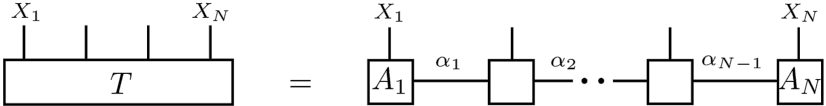
$$\mathcal{L} = \sum_i \log P_i = \sum_i \log(T_i/Z)$$

Learn from a distribution:

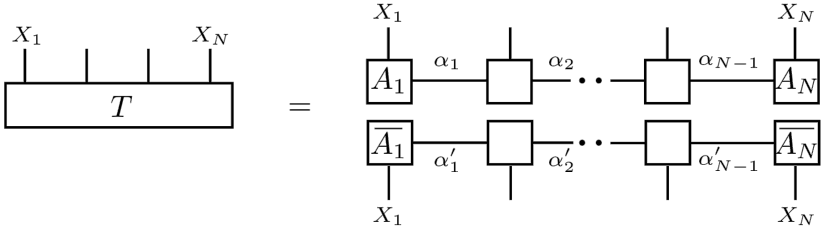
$$\mathcal{D}(P||T/Z) = \sum_x P_x \log \left(\frac{P_x}{T_x/Z} \right)$$

Some models for unsupervised learning

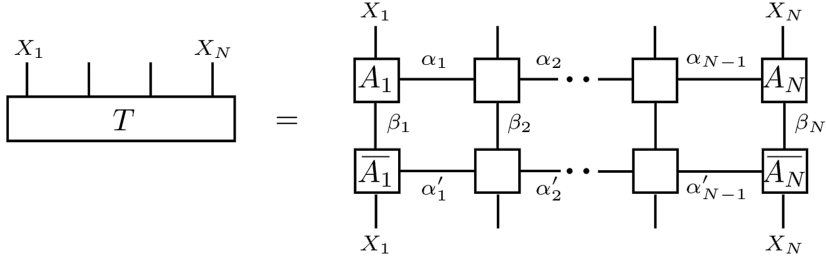
Tensor Train (MPS):



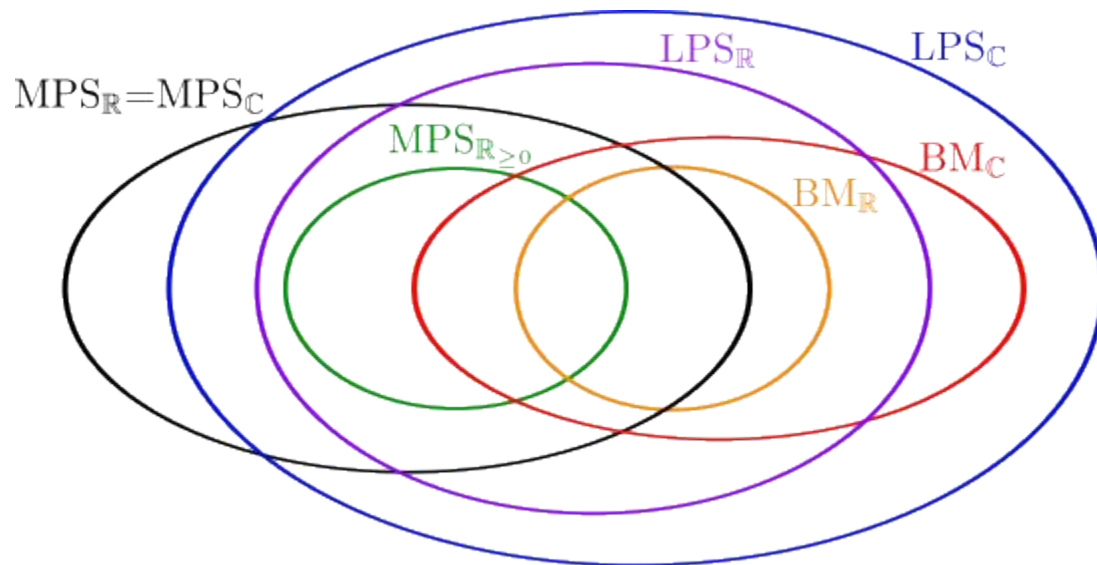
Born Machines:



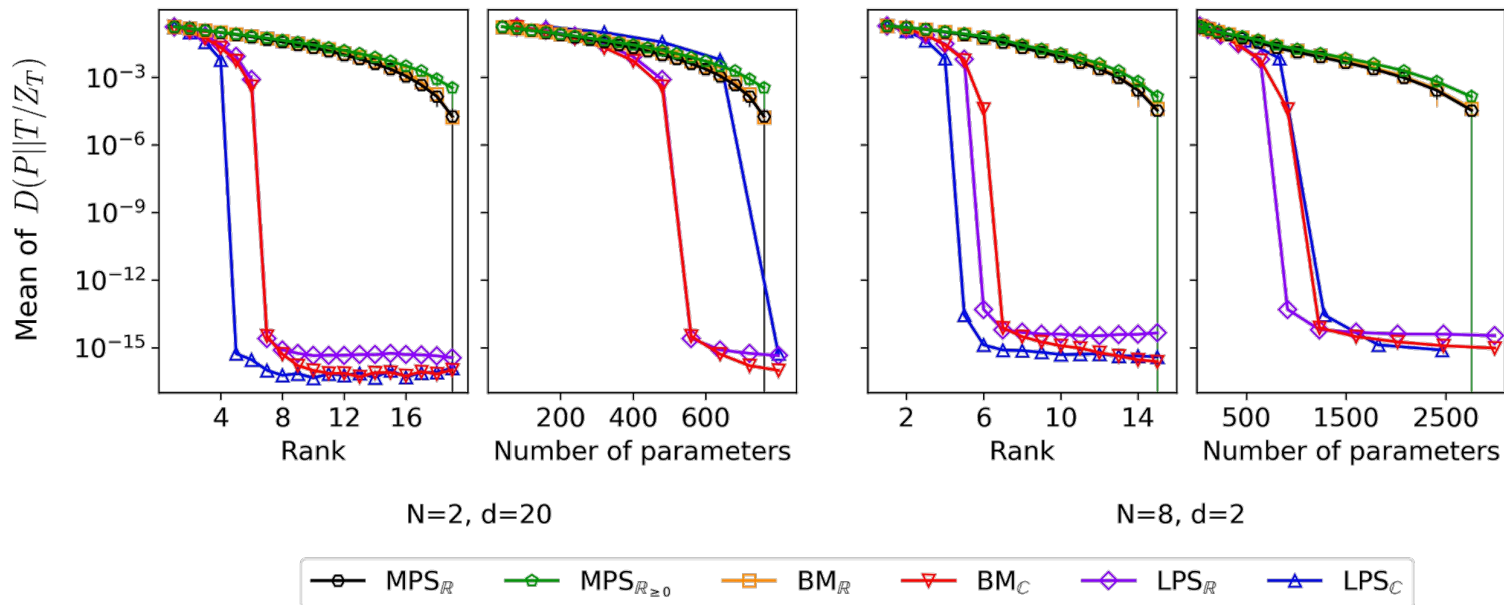
Locally Purified States:



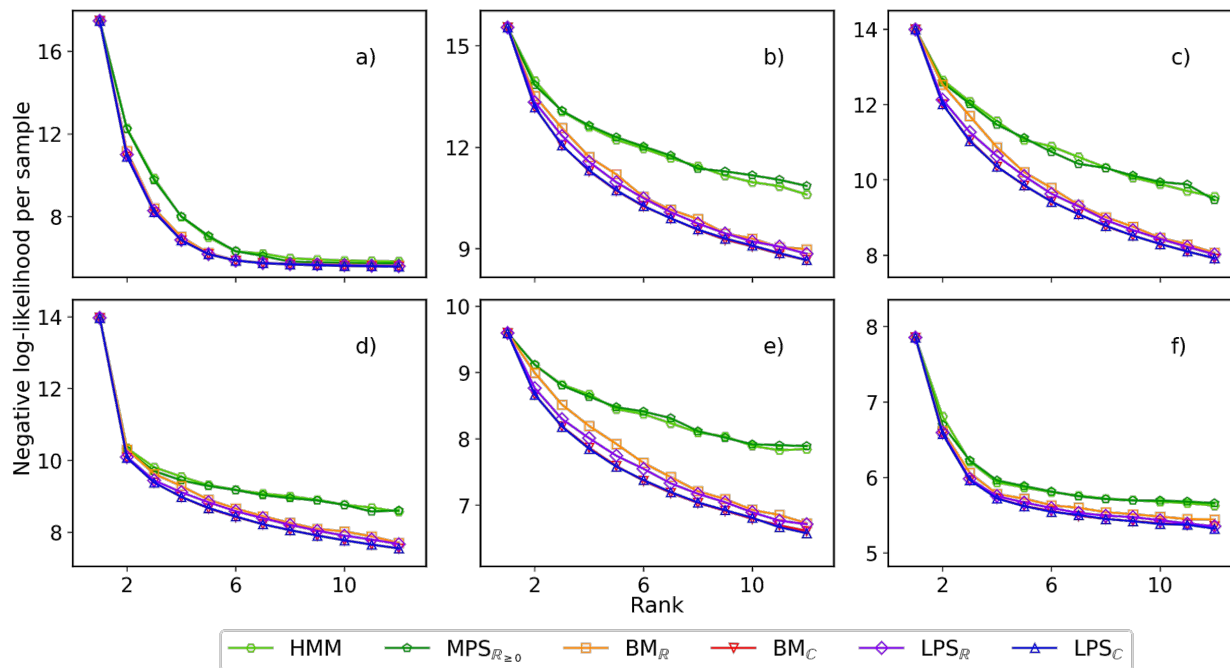
Expressive power



practical applications: random distributions



practical applications: real data sets



conclusions

- quantum mechanics and linear algebra
- linear algebra and tensor networks
- graphical models can be mapped to tensor networks
- tensor networks can be used for
 - classification problems
 - modeling probabilistic theories
- tensor networks can provide deeper mathematical insights

thanks for your attention
