

# DTAE: DEEP TENSOR AUTOENCODER FOR 3-D SEISMIC DATA INTERPOLATION

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## Introduction

The core challenge of seismic data interpolation is how to capture latent spatial-temporal relationships between unknown and known traces in 3-D space. This article presents a basic deep tensor autoencoder (DTAE) and two variants to implicitly learn a data driven, nonlinear, and high-dimensional mapping to explore the complicated relationship among traces without the need for any underlying assumption. The performance benefits of the proposed DTAE-based method are demonstrated in experiments with both synthetic and real field seismic data.

## Problem Statement

**Problem statement:** If we assume that the missing traces are randomly distributed, the observation or sampling process can be represented as

$$\mathcal{T}_\Omega = \mathcal{P}_\Omega(\mathcal{T}). \quad (1)$$

Here,  $\mathcal{P}_\Omega(\cdot)$  denotes the sampling operator, which projects  $\mathcal{T}$  onto the set  $\Omega$  according to the following:

$$\mathcal{P}_\Omega(\mathcal{T}) = \begin{cases} \mathcal{T}(i, j, \cdot), & \text{if } (i, j) \in \Omega, \\ 0, & \text{otherwise,} \end{cases} \quad (2)$$

where the  $(i, j)$ -th vector of  $\mathcal{P}_\Omega(\mathcal{T})$  is equal to  $\mathcal{T}(i, j, \cdot)$  if  $(i, j) \in \Omega$  and zero otherwise.

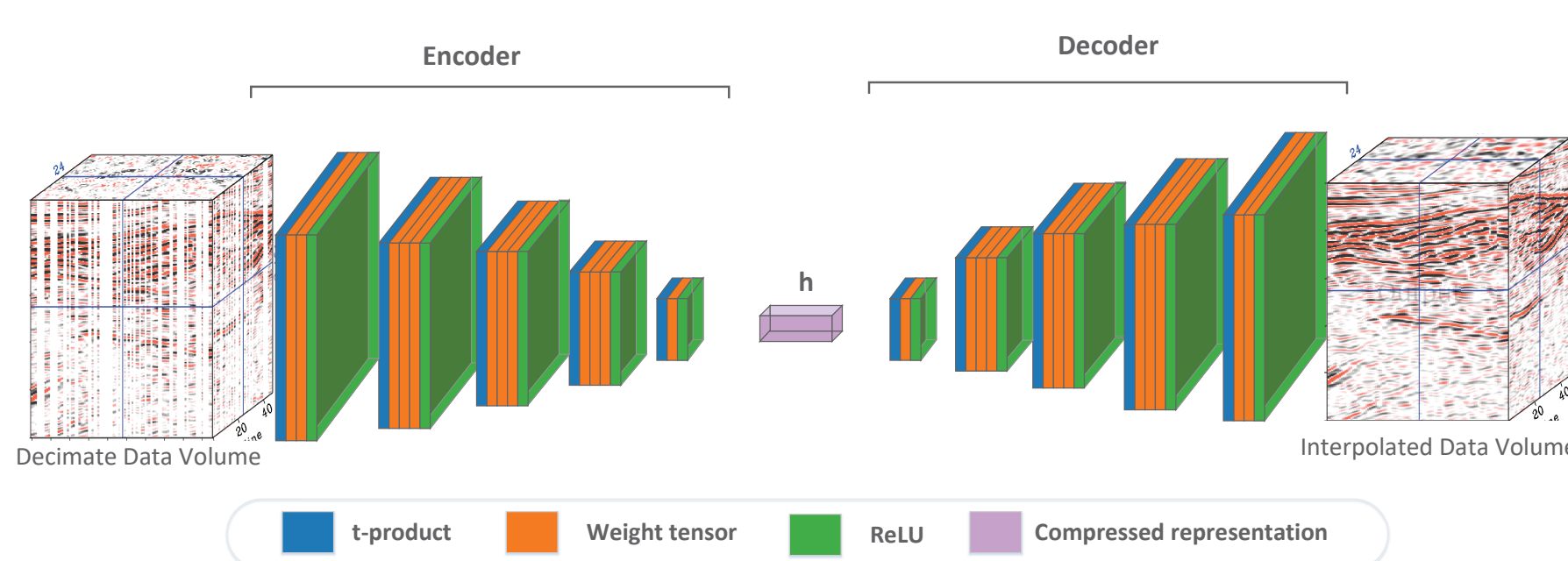
**Problem Formulation:** By introducing DL regression  $f(\mathcal{T}, \Theta)$ , the learning objective of the interpolation task becomes

$$\mathcal{L}_1(\mathcal{T}, \mathcal{T}_\Omega; \Theta) = \operatorname{argmin}_\Theta \mathbb{E}_{\mathcal{T}_\Omega} \|f(\mathcal{T}, \Theta) - \mathcal{T}_\Omega\|_F^2 \quad (3)$$

From this formulation, it is clear that the task here is to learn a function  $f(\cdot)$  with respect to  $\Theta$  that best approximates  $\eta^{-1}(\cdot)$ . Our final solution,  $\hat{\mathcal{T}}$ , can be obtained as follows:

$$\hat{\mathcal{T}} = \eta(\mathcal{T}_\Omega) \odot (1 - \Omega) + \mathcal{T}_\Omega \quad (4)$$

## DTAE model



**Network architecture:** Given a pair of training samples  $(\mathcal{X}_n, \mathcal{Y}_n)$ , we can construct a new DTAE model with the structure. Similar to the matrix AE presented, DTAE is also a t-NN with encoding and decoding layers.

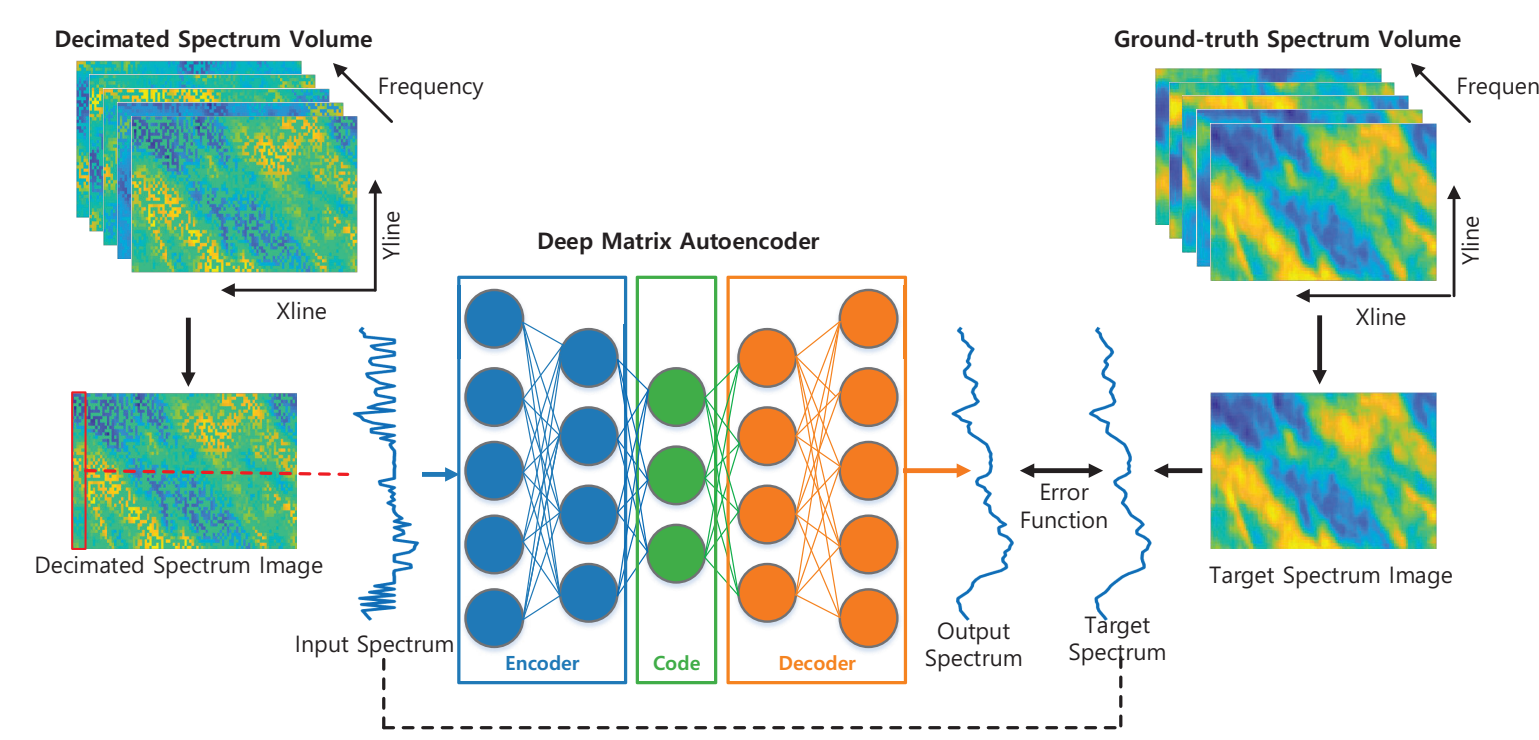
$$\mathcal{X}_{n,\ell} = \mathbf{h}(\mathcal{X}_{n,\ell-1}) = \sigma(\mathcal{W}_{\ell-1} * \mathcal{X}_{n,\ell-1} + \vec{\mathcal{B}}_{\ell-1}) \quad (5)$$

$$\mathbf{g}(\mathcal{X}_{n,\ell-1}) = \sigma(\mathcal{W}_{\ell-1}^\dagger * \mathbf{h}(\mathcal{X}_{n,\ell-1}) + \vec{\mathcal{B}}_{\ell-1}) \quad (6)$$

**Objective function:** In our supervised learning process, training the DTAE model involves finding the parameters  $\Theta = \{\mathcal{W}_\ell, \mathcal{B}_\ell\}_{\ell=1}^K$  such that the expected interpolation error between the output tensor values  $\{\mathcal{X}_{n,\ell}\}_{n=1}^N$  and the desired tensor values  $\{\mathcal{Y}_n\}_{n=1}^N$  is minimized:

$$\mathcal{L}_2(\mathcal{X}_n, \mathcal{Y}_n; \Theta) = \operatorname{argmin}_\Theta \frac{1}{N} \sum_{n=1}^N \frac{1}{2} \|\mathcal{X}_{n,\ell} - \mathcal{Y}_n\|_F^2 \quad (7)$$

## TBP Algorithm



**TBP algorithm:** To optimize model (8), we develop a TBP algorithm to minimize  $\mathcal{L}_3(\mathcal{X}_n, \mathcal{Y}_n; \Theta)$  as a function of  $\Theta$ . That is, we adjust the network parameters  $\Theta$  through layer evolution rules. First, we need to determine how gradient descent modifies  $\mathcal{W}_{\ell-1}$  and  $\mathcal{B}_\ell$ :

$$\begin{aligned} \mathcal{W}_{\ell-1} &\leftarrow \mathcal{W}_{\ell-1} - \alpha \frac{\partial \mathcal{L}_3(\mathcal{W}, \mathcal{B})}{\partial \mathcal{W}_{\ell-1}} \\ \mathcal{B}_\ell &\leftarrow \mathcal{B}_\ell - \alpha \frac{\partial \mathcal{L}_3(\mathcal{W}, \mathcal{B})}{\partial \mathcal{B}_\ell} \end{aligned} \quad (8)$$

**Implementation details:** Taking advantage of this relationship, we derive a solid theoretical framework in which the whole DTAE solution is split into an individual deep matrix autoencoder (DMAE) solution for each frontal slice in the discrete cosine transform (DCT) domain.

### Algorithm 1 TBP Algorithm

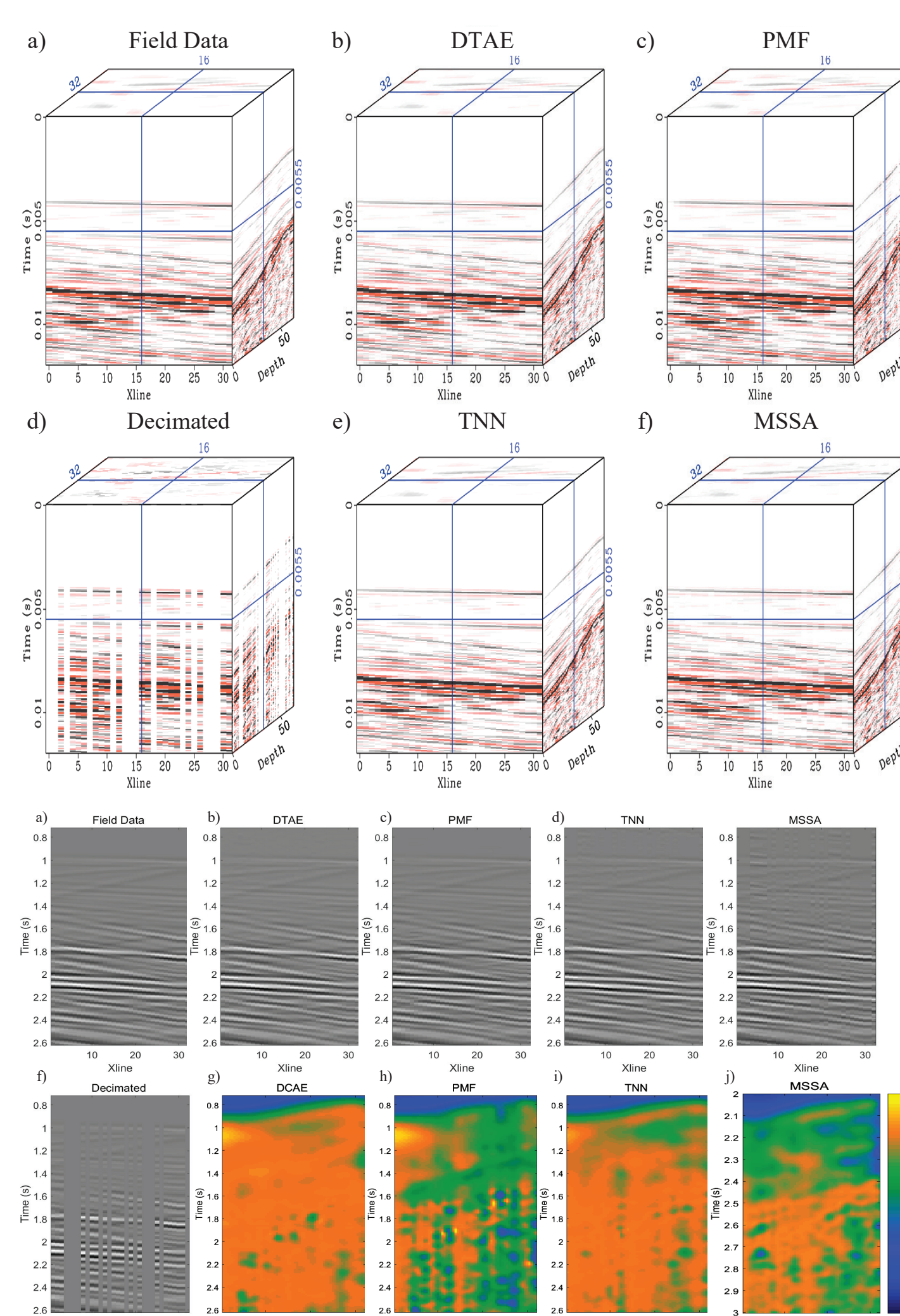
**Require:**  $\mathcal{X}_n, \mathcal{Y}_n, \alpha, N_{bs}, N_r, N_t, \mathcal{P}_\Omega, \mathbb{P}_{AE}$ , Type.

**Ensure:**  $\hat{\mathcal{X}}_n$ .

```
// Training of the DTAE model
 $\tilde{\mathcal{X}}_n \leftarrow \operatorname{det}(\mathcal{X}_n, [], 3), \tilde{\mathcal{Y}}_n \leftarrow \operatorname{det}(\mathcal{Y}_n, [], 3)$ 
for  $k = 1, \dots, N_3$  do
     $f_\theta(\cdot) \leftarrow \operatorname{DMAE}(\tilde{\mathcal{X}}_n^{(k)}, \tilde{\mathcal{Y}}_n^{(k)}, \alpha, N_{bs}, \mathbb{P}_{AE}, \text{type})$ 
end for
// Testing of the DTAE model
for  $k = 1, \dots, N_3$  do
     $\tilde{\mathcal{P}}_n^{(k)} \leftarrow f_\theta(\tilde{\mathcal{X}}_n^{(k)})$ ,  $n \in [N_t]$ 
end for
 $\hat{\mathcal{X}}_n \leftarrow \operatorname{idct}(\tilde{\mathcal{P}}_n, [], 3)$ ,  $n \in [N_t]$ 
 $\hat{\mathcal{X}}_n = \eta(\hat{\mathcal{X}}_n) \odot (1 - \mathcal{P}_\Omega) + \mathcal{X}_n$ 
```

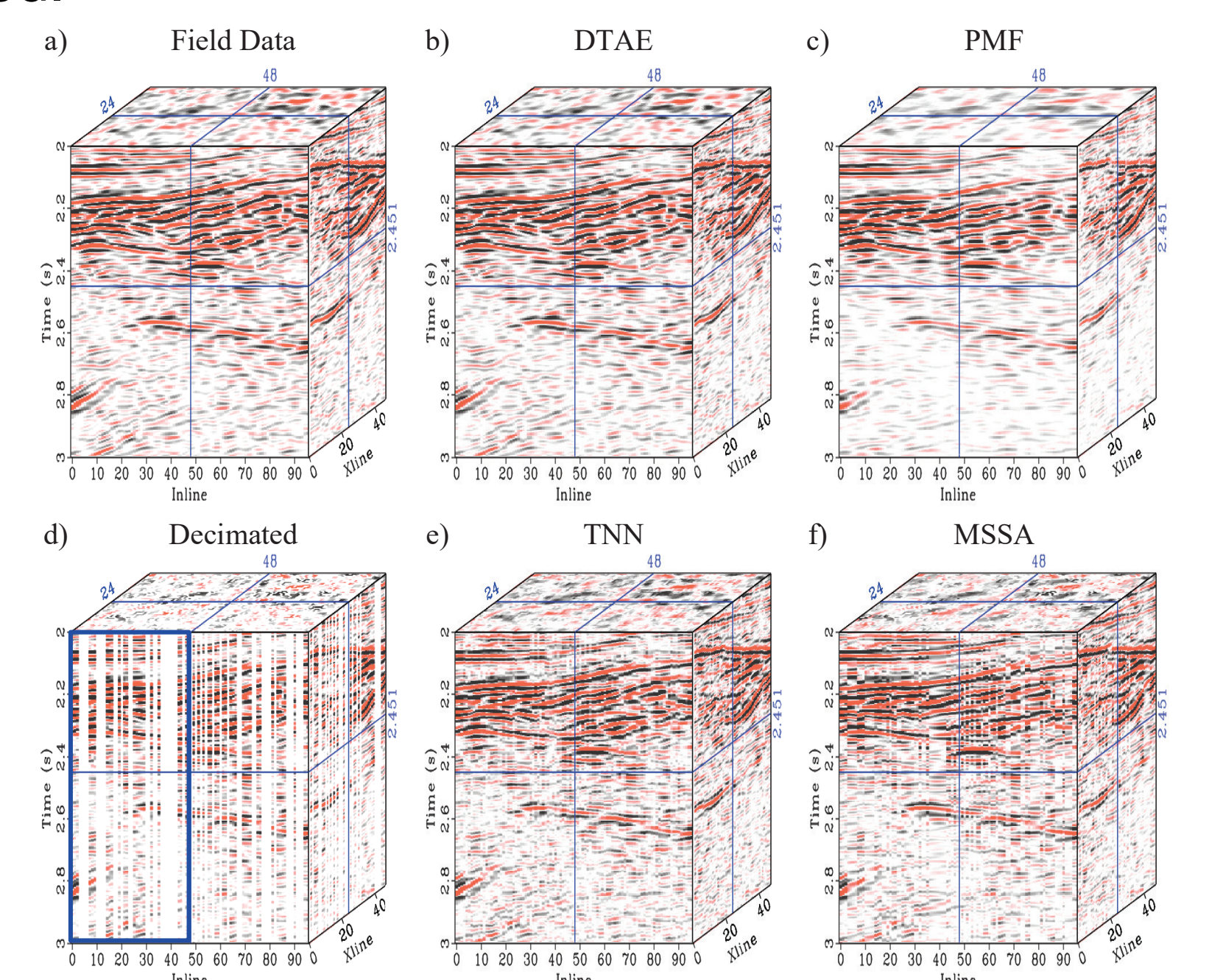
## Validation on Synthetic Data

**Experiment result:** For synthetic VSP data, the superior performance of the DTAE model is clearly apparent.

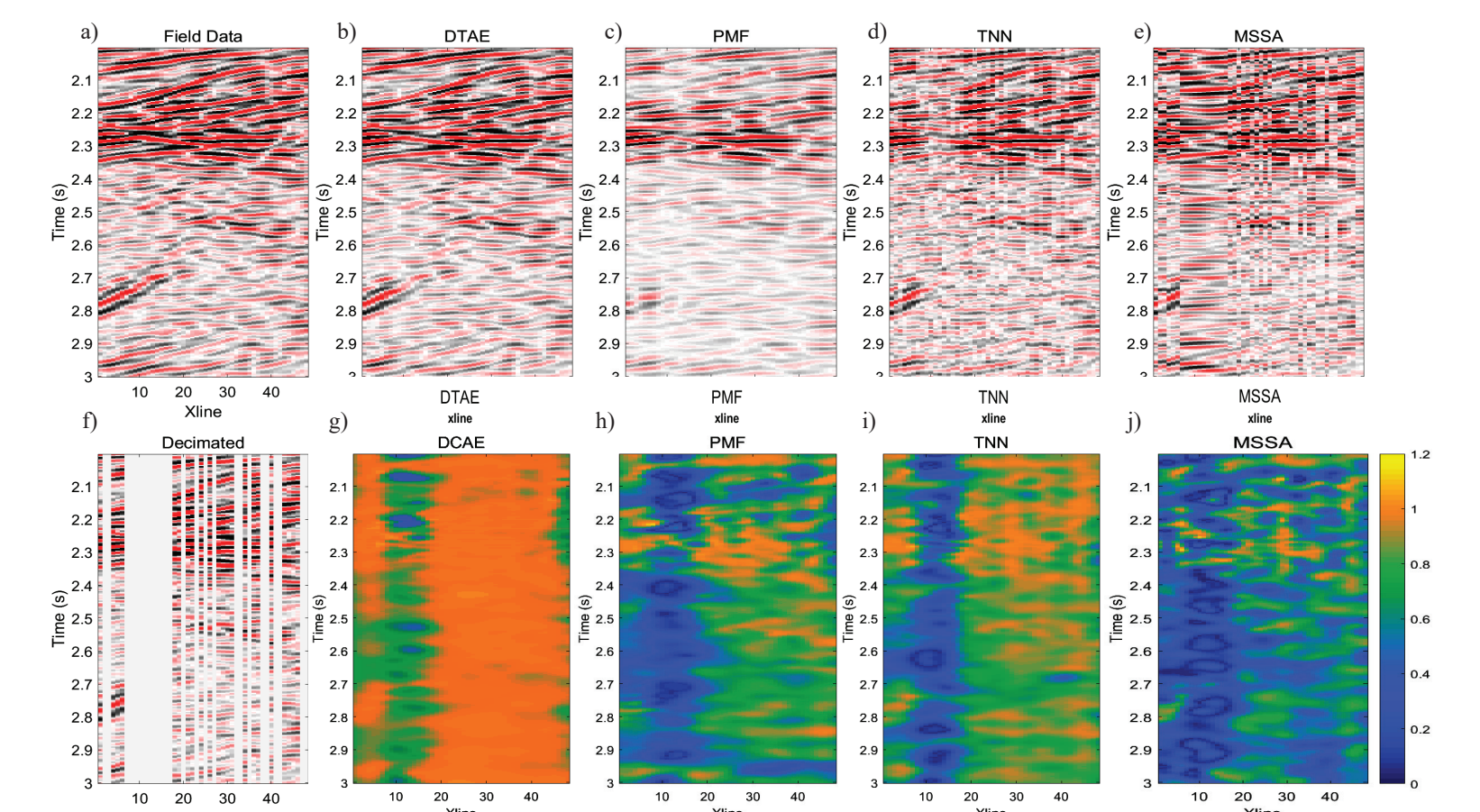


## Validation on Parihaka-3D Data

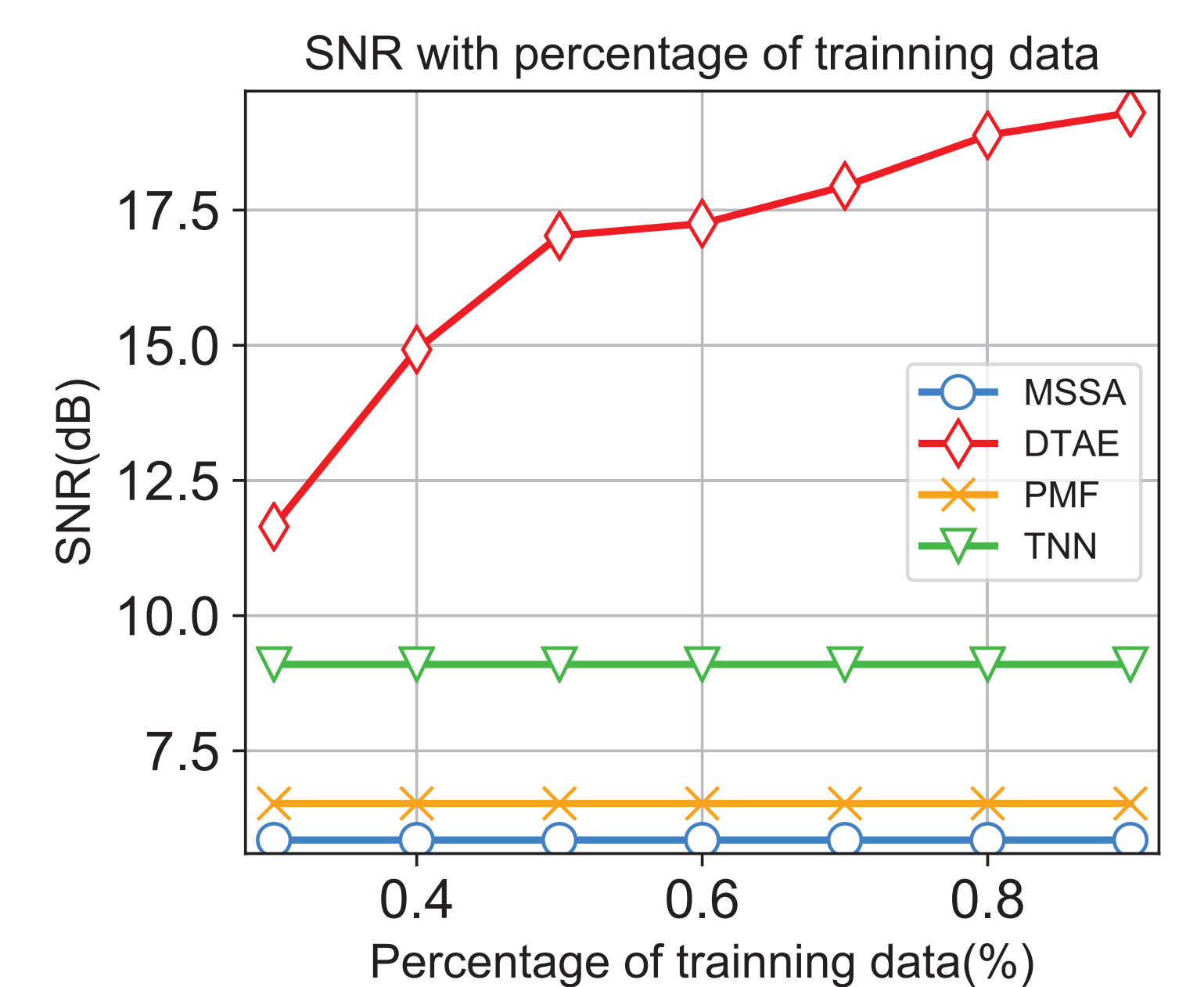
**Experiment result:** To further verify the flexibility of the DTAE method, we apply our method to the Parihaka-3D seismic survey recorded from complex geological structures, with the goal of demonstrating the substantial performance gains of DTAE in the case that the low-rank assumption is not satisfied.



Note that the DTAE network has a nice performance on reconstruction of big gap.



SNR comparison with respect to different percentages of training data in the Parihaka-3D experiment:



## Conclusions

In this article, we proposed a basic DTAE model and two variants for learning a data-driven, nonlinear, high-dimensional mapping to discover the complicated relationship among seismic traces. Experimental results obtained on a synthetic dataset and two real field datasets demonstrated that the proposed DTAE model can achieve smaller interpolation errors than three SOTA interpolation methods.

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## References

[1] F. Qian, Z. Liu, Y. Wang, S. Liao, S. Pan, and G. Hu, "DtAE: Deep tensor autoencoder for 3-d seismic data interpolation," IEEE Trans. Geosci. Remote Sens., early access, May 6, 2021, doi: 10.1109/TGRS.2021.3075968.